CONTENTS

Volume 7, Issue Nos. 1–6

International Journal of

ADAPTIVE CONTROL AND SIGNAL PROCESSING

Issue No. 1, January–February 1993

Construction of a Robust Adaptive Regulator for Time-varying Discrete Time Systems: A. Jerbi, E. W. Kamen and J. F. Dorsey 1

A Skid-to-turn Missile Autopilot Design: the Generalized Predictive Adaptive Control Approach: P. Bendotti and M. M'Saad 13

A New Decentralized Model Reference Adaptive Control for a Class of Interconnected Dynamic Systems Using Variable Structure Design: A.-C. Wu, L.-C. Fu and C.-F. Hsu 33

Partial State Model Reference Adaptive Control of a Rapid Thermal Processor: K. Djebara, B. Dahhou, J. P. Babary, A. Khellaf and C. Ganibal 45

TECHNICAL NOTE

Implementation of Self-tuning Generalized Predictive Controllers for the Process Industry: E. F. Camacho and C. Bordons 63

BOOK REVIEWS 75

Issue No. 2, March–April 1993

Non-linear Learning Control of Robot Manipulators without Requiring Acceleration Measurement: Z. Qu and H. Zhuang 77

Adaptive Predictive Control of Systems with Time-varying Time Delay: G. A. Dumont, A. Elnaggar and A. Elshafei 91

Multi-window Spectrum Estimation—A Linear Algebraic Approach: R. Onn and A. O. Steinhardt 103

Adaptive Feedback Linearization for Position Control of a Switched Reluctance Motor: Analysis and Simulation: L. Ben Amor, L.-A. Dessaint, O. Akhrif and G. Olivier 117

Indexed by 'Artificial Intelligence Abstracts', 'Cambridge Scientific Abstracts', 'CompuMath Citation Index Institute for Scientific Information (ISI)', 'Engineering Index', 'Fluids Abstracts & FLUIDEX', 'INSPEC', 'Research Alert (ISI)', 'SCISEARCH Database (ISI)', 'Shock and Vibration Digest', 'Statistical Theory & Method Abstracts', 'Telecommunications Abstracts'

Adaptive Control of Systems with Unknown Physical Element Values: S. Dasgupta, B. D. O. Anderson and R. J. Kaye 137

TECHNICAL NOTE
Experimental Adaptive Controllers for a Class of Electrohydraulic Servosystems: R. R. Fullmer and S. Ananthakrishnan 151

Issue No. 3, May–June 1993

Robust and Simple Adaptive Control System Design: Z. Iwai, I. Mizumoto and H. Ohtsuka 163

A New Approach to Adaptive Robust Control: W. S. Lee, B. D. O. Anderson, R. L. Kosut and I. M. Y. Mareels 183

Linear and Non-linear Adaptive Control of Alcoholic Fermentation Process: Experimental Results: B. Dahhou, G. Roux and A. Cheruy 213

BOOK REVIEW 235

Issue No. 4, July–August 1993

Model–system Parameter Mismatch in GPC Control: A. W. Ordys 239

Asymptotic Stability of a Class of Adaptive Systems: R. Ortega and A. Fradkov . 255

A Factored Form of the Instrumental Variable Algorithm: S. Niu, D. G. Fisher and D. Xiao 261

Global Partially Decentralized Adaptive Stabilization of Discrete-time Systems: R. Ortega and M. M'Saad 275

Transient Bounds of Dynamic Certainty Equivalent Adaptive Controllers: R. Ortega 291

Non-linear System Identification and Control Based on Neural and Self-tuning Control: A. Abdulaziz and M. Farsi 297

Evaluation of Control Strategies for Anaerobic Digestion Processes: M. Perrier and D. Dochain 309

BOOK REVIEW 323

CONFERENCE DIARY 324

Issue No. 5, September–October 1993

Special Issue: Adaptive Control: Applications to Non-linear Systems and Robotics
Guest Editor: R. Lozano

EDITORIAL 325

Adaptive Control of a Stochastic Non-linear System: an Example: B. Wittenmark . 327

Passive Adaptive Control of Non-linear Systems: I. Kanellakopoulos 339

New Relationships between Lyapunov Functions and the Passivity Theorem: B. Brogliato, R. Lozano and I. D. Landau 353

Non-linear Adaptive Control via Laguerre Expansion of Volterra Kernels: G. A. Dumont and Y. Fu 367

Universal Iterative Learning Control using Adaptive High-gain Feedback: D. H. Owens 383

An Adaptive Force/position Regulator for Robot Manipulators: B. Siciliano and L. Villani 389

Self-tuning Control of Robot Manipulators: S. Nicosia and P. Tomei 405

Learning Gravity Compensation in Robots: Rigid Arms, Elastic Joints, Flexible Links: A. de Luca and S. Panzieri 417

Adaptive Non-linear Speed Control of Induction Motors: T. von Raumer, J. M. Dion and L. Dugard 435

Model Reference Adaptive Control with Unknown Relative Degree: R. G. Moctezuma, R. Lozano and D. A. Suárez 457

Adaptive Performance Enhancement by Iterative Identification and Control Design: R. J. P. Schrama and O. H. Bosgra 475

Issue No. 6, November–December 1993

Adaptive Trajectory/force Control Scheme for Constrained Robot Manipulators: E. V. Panteley and A. A. Stotsky 489

Blind Adaptation of Decision Feedback Equalizers: Gross Convergence Properties: R. A. Kennedy, B. D. O. Anderson and R. R. Bitmead 497

Performance Analysis of the Forgetting Factor RLS Algorithm: L. Guo, L. Ljung and P. Priouret 525

An Improved Variable Structure Model-following Control for Robotic Manipulators: Man Zhihong and M. Palaniswami 539

BOOK REVIEW 563

AUTHOR INDEX 565

KEY WORD INDEX 567